

Before we start: What is $L^+ |m\rangle$?

$$\begin{aligned} L_3 L^+ |m\rangle &= L_3 (L_1 + iL_2) |m\rangle = L_3 L_1 |m\rangle + iL_3 L_2 |m\rangle \\ &= m\hbar L_1 |m\rangle + im\hbar L_2 |m\rangle + [L_3, L_1] |m\rangle + i[L_3, L_2] |m\rangle \\ &= m\hbar L^+ |m\rangle + i\hbar L_2 |m\rangle + \hbar L_1 |m\rangle \\ &= (m+1)\hbar L^+ |m\rangle \end{aligned}$$

$$\Rightarrow L^+ |m\rangle \propto |m+1\rangle$$

Normalization:

$$\begin{aligned} \langle m | L^+ L^+ |m\rangle &= \langle m | L_1^2 + L_2^2 |m\rangle = \langle m | L^2 |m\rangle - \langle m | L_3^2 |m\rangle \\ &= \ell(\ell+1) - |m|^2 \quad (*) \end{aligned}$$

1a) Scattering of a wave coming from the left, at a δ -shaped peak (repulsive)

$$\begin{aligned} \text{b) } \Psi_{\text{II}}(0) &= \Psi_{\text{I}}(0) \quad \Psi'_{\text{II}}(0) - \Psi'_{\text{I}}(0) = \lim_{\epsilon \rightarrow 0} \int_{-\epsilon}^{\epsilon} -\frac{2m}{\hbar^2} (E - \delta(x)V_0) \Psi(x) dx \\ &= \frac{2m}{\hbar^2} V_0 \Psi(0) = \frac{2m}{\hbar^2} V_0 S \end{aligned}$$

$$\text{c) } e^0 + R e^0 = S e^0 \Rightarrow 1 + R = S$$

$$iqS - iq + iqR = \frac{2m}{\hbar^2} V_0 S \Rightarrow iq(S + R - 1) = \frac{2m}{\hbar^2} V_0 S$$

$$\Rightarrow iq(2S - 2) = \frac{2m}{\hbar^2} V_0 S \Rightarrow +iq(S - 1) = \frac{m}{\hbar^2} V_0 S$$

$$\Rightarrow -iq = \left(\frac{m}{\hbar^2} V_0 - iq \right) S \Rightarrow S = \frac{iq}{\left(iq - \frac{mV_0}{\hbar^2} \right)}$$

$$\text{d) } j_{x<0} = -\frac{\hbar q}{m} (R^* R - 1) = \frac{\hbar q}{m} (1 - R^* R)$$

$$j_{x>0} = \frac{\hbar q}{m} S^* S$$

Note that $j_{x<0} = j_{x>0}$ because $2S^* S = S^* + S$. This is a simple version of the optical theorem

$$\begin{aligned}
 2a) \quad \Psi &= K (x+y+2z) e^{-\alpha r} \\
 &= K (r \sin \theta \cos \varphi + r \sin \theta \sin \varphi + 2r \cos \theta) e^{-\alpha r} \\
 &= (\sin \theta \cos \varphi + \sin \theta \sin \varphi + 2 \cos \theta) K r e^{-\alpha r}
 \end{aligned}$$

$$\begin{aligned}
 \cos \theta &= \sqrt{\frac{4\pi}{3}} Y_{1,0} & \sin \theta \sin \varphi &= \sqrt{\frac{2\pi}{3}} i (Y_{1,1} + Y_{1,-1}) \\
 \sin \theta \cos \varphi &= \sqrt{\frac{2\pi}{3}} (-Y_{1,1} + Y_{1,-1})
 \end{aligned}$$

$$\Rightarrow \Psi(r, \theta, \varphi) = \left[\sqrt{\frac{2\pi}{3}} (-Y_{1,1} + Y_{1,-1}) + \sqrt{\frac{2\pi}{3}} i (Y_{1,1} + Y_{1,-1}) + 2\sqrt{\frac{4\pi}{3}} Y_{1,0} \right] K r e^{-\alpha r}$$

$$b) \frac{1}{\hbar} L_z \Psi = \left[\sqrt{\frac{2\pi}{3}} (-Y_{1,1} - Y_{1,-1}) + \sqrt{\frac{2\pi}{3}} i (Y_{1,1} - Y_{1,-1}) \right] K r e^{-\alpha r}$$

$$\Psi^* = \left[\sqrt{\frac{2\pi}{3}} (-Y_{1,1}^* + Y_{1,-1}^*) - \sqrt{\frac{2\pi}{3}} i (Y_{1,1}^* + Y_{1,-1}^*) + 2\sqrt{\frac{4\pi}{3}} Y_{1,0}^* \right]$$

$$\begin{aligned}
 \int d\Omega \Psi^* \frac{L_z}{\hbar} \Psi &= K^2 r^2 e^{-2\alpha r} \left[\left(-\sqrt{\frac{2\pi}{3}} + i\sqrt{\frac{2\pi}{3}} \right) \left(-\sqrt{\frac{2\pi}{3}} - i\sqrt{\frac{2\pi}{3}} \right) \right. \\
 &\quad \left. + \left(-\sqrt{\frac{2\pi}{3}} - i\sqrt{\frac{2\pi}{3}} \right) \left(\sqrt{\frac{2\pi}{3}} - i\sqrt{\frac{2\pi}{3}} \right) \right] \\
 &= K^2 r^2 e^{-2\alpha r} \left[\frac{2\pi}{3} + \frac{2\pi}{3} - \frac{2\pi}{3} - \frac{2\pi}{3} \right] = 0
 \end{aligned}$$

$$\Rightarrow \langle \Psi | L_z | \Psi \rangle = 0$$

$$\text{also, } L^2 Y_{1,*} = \hbar^2 2 Y_{1,*} = \hbar^2 (\ell+1)\ell Y_{1,*}$$

there are only harmonics with $\ell=1$ in the wave

$$\Rightarrow \langle \Psi | \frac{L^2}{\hbar^2} | \Psi \rangle = 2$$

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3a) The Hamiltonian commutes with total angular momentum:

$$[\hat{L}^2, \hat{H}] = [\hat{L}^2, g\hat{L}^2] + [\hat{L}^2, B \cdot \hat{L}] = 0 + 0 = 0$$

What is $\langle l_1, m_1 | \hat{H} | l_2, m_2 \rangle$?

Trick: Insert $\hat{L}^2$:

$$\begin{aligned} \langle l_1, m_1 | \hat{H} \frac{\hat{L}^2}{\hbar^2} | l_2, m_2 \rangle &= (l_2+1)l_2 \langle l_1, m_1 | \hat{H} | l_2, m_2 \rangle \\ &= \langle l_1, m_1 | \frac{\hat{L}^2}{\hbar^2} \hat{H} | l_2, m_2 \rangle = (l_1+1)l_1 \langle l_1, m_1 | \hat{H} | l_2, m_2 \rangle \end{aligned}$$

So, if $l_1 \neq l_2$, we get $\langle l_1, m_1 | \hat{H} | l_2, m_2 \rangle = 0$

We see again that angular momentum is conserved

$$\Rightarrow \hat{H} = \sum_{l=0}^{\infty} \sum_{m, m'=-l}^l h_{m, m'}^{(l)} |l, m\rangle \langle l, m'|$$

b) Let $l=1$ $\langle m_1 | \hat{H} | m_2 \rangle = 2g\hbar^2 + B_i \langle m_1 | \hat{L}_i | m_2 \rangle$

i) $\langle m_1 | \hat{L}_3 | m_2 \rangle = \hbar m_2 \delta_{m_1, m_2}$

$$\hat{L}^+ = \hat{L}_1 + i\hat{L}_2 \quad \hat{L}^- = \hat{L}_1 - i\hat{L}_2$$

ii) $\langle m_1 | \hat{L}_1 | m_2 \rangle = \frac{1}{2} \langle m_1 | \hat{L}^+ | m_2 \rangle + \frac{1}{2} \langle m_1 | \hat{L}^- | m_2 \rangle$

$$\stackrel{(*)}{=} \frac{1}{2} \frac{1}{\sqrt{2}} \delta_{m_1, m_2+1} + \frac{1}{2} \frac{1}{\sqrt{2}} \delta_{m_1, m_2-1} = \frac{1}{2} \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\langle m_1 | \hat{L}_2 | m_2 \rangle = -\frac{i}{2} \langle m_1 | \hat{L}^+ - \hat{L}^- | m_2 \rangle = -\frac{i}{2} \langle m_1 | \hat{L}^+ | m_2 \rangle + \frac{i}{2} \langle m_1 | \hat{L}^- | m_2 \rangle$$

$$= -\frac{i\hbar}{\sqrt{2}} \delta_{m_1, m_2+1} + \frac{i\hbar}{\sqrt{2}} \delta_{m_1, m_2-1}$$

$$= -\frac{i\hbar}{\sqrt{2}} \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix} \begin{matrix} m_1=1 \\ m_1=0 \\ m_1=-1 \end{matrix}$$

$$\begin{matrix} m_2=1 & m_2=0 & m_2=-1 \end{matrix}$$

$$[K_x, K_y] = i\hbar K_z$$

$$[K_y, K_z] = i\hbar K_x$$

$$[K_z, K_x] = i\hbar K_y$$

3c, In the Heisenberg picture,

$$\hat{L}(t) = e^{i\frac{\hat{H}t}{\hbar}} \hat{L}(0) e^{-i\frac{\hat{H}t}{\hbar}}$$

$$\frac{d}{dt} \hat{L}_i(t) = \frac{i}{\hbar} e^{i\frac{\hat{H}t}{\hbar}} [\hat{H}, \hat{L}_i] e^{-i\frac{\hat{H}t}{\hbar}} = \frac{i}{\hbar} [\hat{H}, \hat{L}_i(t)]$$

$$[\hat{H}, \hat{L}_i] = B_j [\hat{L}_j, \hat{L}_i] = -i\hbar \epsilon_{ijk} B_j \hat{L}_k = -i\hbar \vec{B} \times \vec{L}$$

$$\Rightarrow \frac{d}{dt} \hat{L}_i(t) = e^{i\frac{\hat{H}t}{\hbar}} (\vec{B} \times \vec{L}) e^{-i\frac{\hat{H}t}{\hbar}} = \vec{B} \times \vec{L}(t)$$

d, $\vec{B} = (B, 0, 0)$ $|\psi(t=0)\rangle = |l, m=1\rangle$

$$\langle \vec{L} \rangle(t) = \langle l=1, m=1 | \vec{L}(t) | l=1, m=1 \rangle$$

$$\frac{d}{dt} \vec{L}(t) = \begin{pmatrix} B \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} L_x \\ L_y \\ L_z \end{pmatrix} = \begin{pmatrix} 0 \\ -B \cdot L_z(t) \\ B \cdot L_y(t) \end{pmatrix}$$

$$\begin{pmatrix} \langle L_x \rangle \\ \langle L_y \rangle \\ \langle L_z \rangle \end{pmatrix} = B \begin{pmatrix} 0 \\ -\langle L_z \rangle \\ \langle L_y \rangle \end{pmatrix} \quad \langle L_y \rangle(0) = 0 \quad \langle L_z \rangle(0) = 0$$

$$\Rightarrow \langle L_y \rangle(t) = \sin(-Bt)$$

$$\langle L_z \rangle(t) = \cos(-Bt)$$

We see a precession around the B -field as an axis