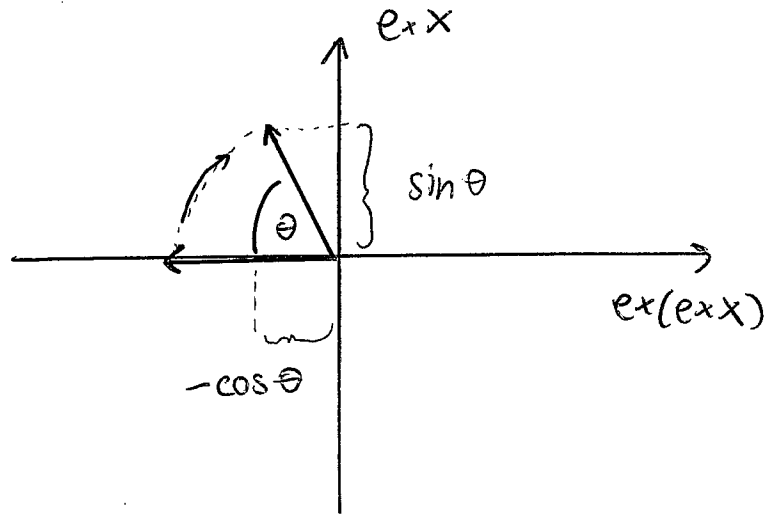


1a)



$$b) \quad \frac{d}{d\theta} \chi(\theta) = \sin \theta (e_x(e_x x)) + \cos \theta (e_x x)$$

$$e_x x(\theta) = -\cos \theta [e_x(e_x(e_x x))] + \sin \theta e_x(e_x x)$$

$$a \times (b \times c) = b(ac) - c(ab)$$

$$e_x(e_x(e_x x)) = e(e(e_x x)) - (e_x x)(ee) = -e_x x$$

$$\Rightarrow e_x x(\theta) = \cos \theta (e_x x) + \sin \theta (e_x(e_x x)) = \frac{d}{d\theta} \chi(\theta) \quad \#$$

$$c) \quad \hat{\rho}(\theta) = e^{i \vec{e} \cdot \hat{L} \frac{\theta}{\hbar}} \hat{\rho} e^{-i \vec{e} \cdot \hat{L} \frac{\theta}{\hbar}}$$

$$\begin{aligned} \frac{d}{d\theta} \hat{\rho}_j(\theta) &= e^{i\theta} \left(\frac{i}{\hbar} \vec{e} \cdot \hat{L} \right) \hat{\rho}_j e^{-i\theta} + e^{i\theta} \hat{\rho}_j \left(-\frac{i}{\hbar} \vec{e} \cdot \hat{L} \right) e^{-i\theta} \\ &= \frac{i}{\hbar} e^{i\theta} [\vec{e} \cdot \hat{L}, \hat{\rho}_j] e^{-i\theta} \end{aligned}$$

$$[\hat{L}_i, \hat{\rho}_j] = i\hbar \epsilon_{ijk} \hat{p}_k$$

$$= -e^{i\theta} \epsilon_{ijk} \epsilon_{ijl} e^{-i\theta} = [\vec{e} \times \hat{\rho}(\theta)]_j$$

$$d) T_{\vec{e},\theta} = e^{-i\vec{e}\cdot\vec{L}\frac{\theta}{\hbar}}$$

$$T_{\vec{e},\theta} T_{\vec{e},\theta}^\dagger = e^{-i\vec{e}\cdot\vec{L}\frac{\theta}{\hbar}} e^{i\vec{e}\cdot\vec{L}\frac{\theta}{\hbar}} = 11, \text{ i.e. } T_{\vec{e},-\theta} = T_{\vec{e},\theta}^\dagger = T_{\vec{e},\theta}^{-1}$$

Trick

$$T_{\vec{e},\theta}^\dagger \hat{p} T_{\vec{e},\theta} |\vec{p}\rangle = (R(\vec{e},\theta) \hat{p}) |\vec{p}\rangle = (R(\vec{e},\theta) \vec{p}) |\vec{p}\rangle$$

$\nwarrow$ Operator $\swarrow$ Number
 $\uparrow$
 now we can substitute the eigenvalue $\vec{p}$

$$\Rightarrow \hat{p} (T_{\vec{e},\theta} |\vec{p}\rangle) = T_{\vec{e},\theta} (R(\vec{e},\theta) \hat{p}) |\vec{p}\rangle$$

$$= T_{\vec{e},\theta} (R(\vec{e},\theta) \vec{p}) |\vec{p}\rangle = (R(\vec{e},\theta) \vec{p}) (T_{\vec{e},\theta} |\vec{p}\rangle)$$

acts on

$$\Rightarrow [(T_{\vec{e},\theta} |\vec{p}\rangle) \propto |R(\vec{e},\theta) \vec{p}\rangle]$$

Sheet 8 2-1

Short digression: Conservation Laws in QM and Classical Mechanics

Classical

Dynamics: $H(q_i, p_i)$, $\dot{q}_i = \frac{\partial H}{\partial p_i}$, $\dot{p}_i = -\frac{\partial H}{\partial q_i}$

Observables: $f(q, p)$

$$\frac{d}{dt} f(q, p) = \frac{\partial f}{\partial q_i} \dot{q}_i + \frac{\partial f}{\partial p_i} \dot{p}_i = \frac{\partial f}{\partial q_i} \frac{\partial H}{\partial p_i} - \frac{\partial f}{\partial p_i} \frac{\partial H}{\partial q_i} \equiv \{f, H\}$$

"Poisson bracket"

Conserved quantities: f conserved $\Leftrightarrow \{f, H\} = 0$

Quantum

Dynamics: $\hat{H}(\hat{q}_i, \hat{p}_i)$

Observables: $\hat{f}(\hat{q}_i, \hat{p}_i)$

$$\frac{d}{dt} \hat{f}(\hat{q}, \hat{p}) = -\frac{i}{\hbar} [\hat{f}, \hat{H}]$$

Conserved quantities: $\hat{f}$ conserved $\Leftrightarrow [\hat{f}, \hat{H}] = 0$

Taking angular momentum as an example, we will see that both in the classical and the quantum case, the conserved observables generate symmetry transformations of the Hamiltonian

General case: Noether theorem

Classical

Let H be invariant under rotations, i.e. $\frac{d}{d\theta} H(q(\theta), p(\theta)) = 0$

$$\Leftrightarrow \frac{\partial H}{\partial q_i} (\vec{e} \times \vec{q})_i + \frac{\partial H}{\partial p_i} (\vec{e} \times \vec{p})_i = 0 \Leftrightarrow \{H, \vec{e} \cdot (\vec{q} \times \vec{p})\} = 0$$

$$\Leftrightarrow \{H, \vec{e} \cdot \vec{L}\} = 0$$

$\Rightarrow$ Angular momentum in the $\vec{e}$ -direction is conserved, $\vec{e}$ was arbitrary $\Rightarrow \vec{L}$ is conserved

In the Poisson bracket, $\vec{L}$ generates infinitesimal rotations of an observable

Quantum

Let $\hat{H}$ be invariant under rotations $\Leftrightarrow \frac{d}{d\theta} \left(e^{i\vec{e}_0 \cdot \hat{L} \frac{\theta}{\hbar}} \hat{H} e^{-i\vec{e}_0 \cdot \hat{L} \frac{\theta}{\hbar}} \right) = 0$

$$\Leftrightarrow e^{i\vec{e}_0 \cdot \hat{L}} [\vec{e}_0 \cdot \hat{L}, \hat{H}] e^{-i\vec{e}_0 \cdot \hat{L}} = 0$$

$$\Leftrightarrow [\vec{e}_0 \cdot \hat{L}, \hat{H}] = 0 \quad (*)$$

Again, $\hat{L}$ generates the symmetry transformation, and $[\hat{L}, \hat{H}] = 0$ tells us that angular momentum is conserved.

Conclusion

[Generators of symmetries are conserved observables]

Example: $\hat{H} = \frac{\hat{p}_0^2}{2m} + V(\hat{x})$ $V(x) = V(|x|)$

$$\begin{aligned} T_{\vec{e}_0}^\dagger \hat{p}_0 \hat{p}_0 T_{\vec{e}_0} &= T_{\vec{e}_0}^\dagger \hat{p}_j T_{\vec{e}_0} T_{\vec{e}_0}^\dagger \hat{p}_j T_{\vec{e}_0} \\ &= (R_{j\frac{1}{2}}(\vec{e}, \theta) \hat{p}_j) (R_{j\frac{1}{2}}(\vec{e}, \theta) \hat{p}_j) = \hat{p}_0^T \underbrace{R^T(\vec{e}, \theta) R(\vec{e}, \theta)}_{=1} \hat{p} = \hat{p}^2 \end{aligned}$$

Potential: $V(x) = \sum a_n x^n$

$$T_{\vec{e}_0}^\dagger V(\hat{x}) T_{\vec{e}_0} = \sum_{n=0}^{\infty} a_n \left(T_{\vec{e}_0}^\dagger \hat{x}_j T_{\vec{e}_0} \right)^n = V(R(\vec{e}, \theta) \hat{x}) = V(\hat{x})$$

$$\Rightarrow \frac{d}{d\theta} \left(e^{i\vec{e}_0 \cdot \hat{L} \frac{\theta}{\hbar}} \hat{H} e^{-i\vec{e}_0 \cdot \hat{L} \frac{\theta}{\hbar}} \right) = 0 \quad (*) \Rightarrow [\vec{e}_0 \cdot \hat{L}, \hat{H}] = 0$$

$\Rightarrow \hat{L}$ is conserved